

# MT310 - Replaced by Digitek Cobra

## DAS4 Data Logger

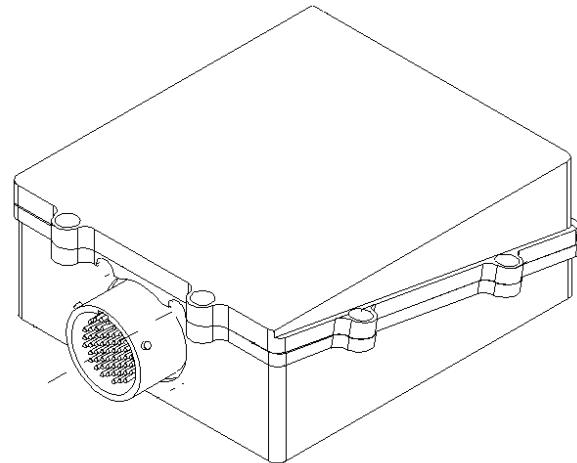


DAS4 is a versatile data acquisition unit developed by Magneti Marelli for racing applications which require high resolution data from a large number of channels.

The unit is equipped with two CAN controllers allowing greater flexibility in the design of the on-board system architecture.

Communications with the PC analysis and programming software is via a point-to-point Ethernet line using a standard network adapter card (*not supplied*).

The 16 single-ended analogue inputs and 4 input capture channels complement the 2 CAN lines making the unit ideal for applications which combine chassis and engine analysis.



### Characteristics

- 24 Mbytes memory
- Sampling rates up to 1000 Hz
- Up to 200 logged channels
- Up to 40 kbytes/sec logging rate
- 16 analogue inputs
- 4 wheel speed inputs
- Event-triggered high-speed burst logging
- 2 CAN lines
- High speed download via standard 10baseT Ethernet card (*not supplied*)
- Real time telemetry output (RS232, 4.8 kbps)
- Compatible with wide range of dashboards
- Free WINTAX2 LITE analysis software (compatible Win95/98/NT)
- Supplied with MIL-spec. mating loom connector
- Small, light, robust

### Ordering Information

Description		Order code
MT310	DAS4 Data Logger + WINTAX2 LITE + Flying connector	083816041300

CAN terminations selected on connector

For further details please contact

MM Competition Systems Ltd  
Unit 3 Old Station Business Park, Compton, Berkshire  
RG20 6NE  
England

Tel +44(0)8707 444666  
Fax +44(0)8707 444888  
[www.mmcompsys.com](http://www.mmcompsys.com)  
[mail@mmcompsys.com](mailto:mail@mmcompsys.com)

## Technical data

### Logging

Memory .....	24 Mbytes
Logging capacity.....	20 kbytes/s
Sampling frequency.....	1...1000 Hz
Channels .....	200 max.
Max. lap length (firmware limit).....	3 Mbytes

### Analogue Inputs

Single ended inputs (AIN1...16).....	16
Input voltage range.....	0...5 V
Input filters	
anti-aliasing.....	500 Hz
Resolution .....	12 Bit
Precision.....	± 1 LSB
Over voltage protection.....	60 V .....for 1 s

### Digital Inputs

Input capture (IC1...4) .....	4
threshold .....	3.35 V
max. frequency.....	5 kHz
max. input voltage .....	± 25V
representation .....	2 µs/LSB
pull-up to 5 V .....	10 kΩ
Counters.....	4
source .....	IC1..4
representation .....	16-bit signed integer
On/Off.....	2
type .....	TTL
trigger.....	rising edge
applications .....	beacon → track marker .....marker → manual marker

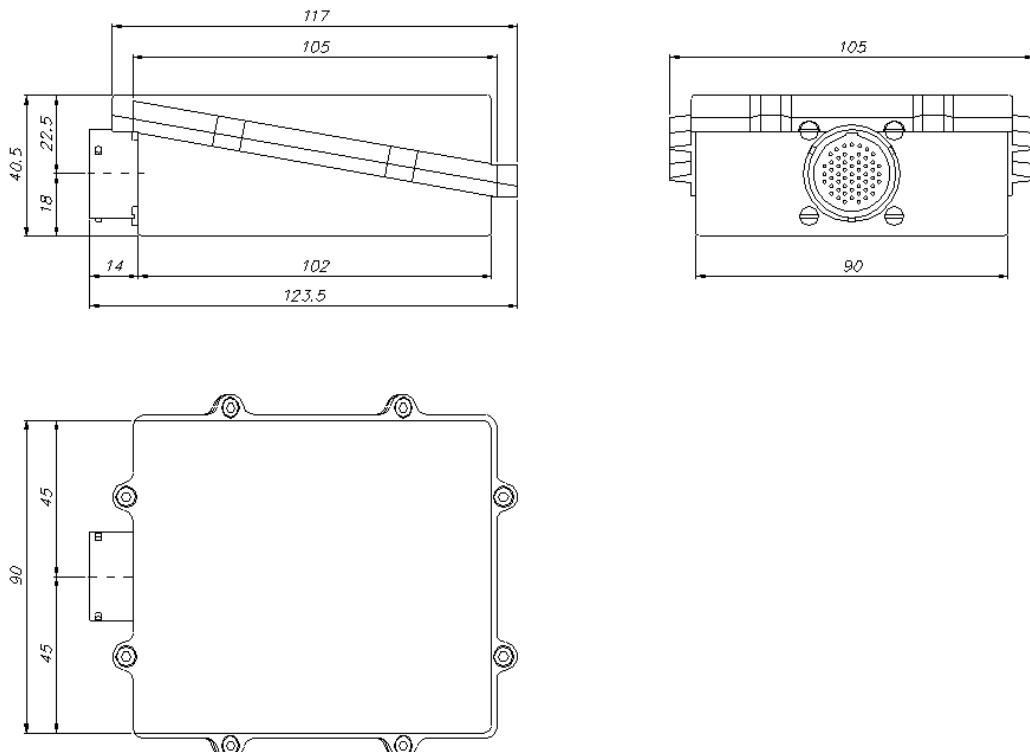
### Communications

CAN lines .....	2
speed.....	1 Mbaud
terminations .....	pinout selectable
identifiers .....	standard 11 bit
applications.....	data acquisition .....dashboard comm.s
Ethernet .....	1
physical.....	10BASE-T
protocol.....	NetBEUI
applications.....	download .....logger setup
RS232 .....	1
applications.....	code load real time telemetry

### Electrical / Mechanical Characteristics

Voltage reference.....	3
voltage .....	5 V
max combined current.....	50 mA
Power supply .....	7...18 V dc
( <i>without other sensors</i> ).....	typ. 160 mA
protection.....	load dump .....polarity inversion .....short circuit to VBatt & GND
Operating temperature .....	0...70 °C
Shock.....	50 g
.....	10 ms
Vibration tested at .....	10 g .....1500 Hz
Dimensions	
(box w/o connector) .....	117x105x40.5 mm
Weight.....	380 g
Container .....	Black anodised aluminium IP64
Connector (Amphenol part no.s).....	
logger.....	SJT00RT-16-35PN
loom.....	SJTG06RT-16-35SN

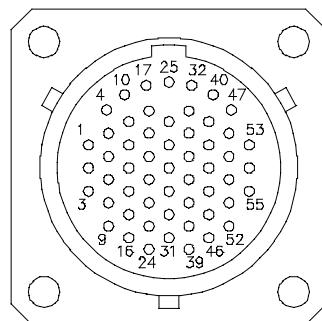
## Dimensions



All dimensions in millimetres

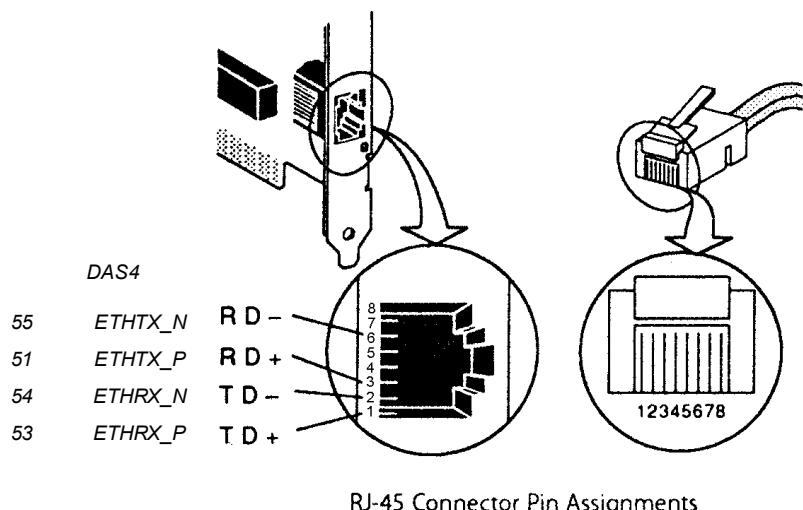
## Connector Pin Out

DAS4 pin-out: SJT00RT-16-35PN								
Pin	Name	descr.	Pin	name	descr.	Pin	name	descr.
1	AIN1	0...5V input #1	21	AGND	analogue ground <sup>1</sup>	41	RX485_P	not used
2	AIN2	0...5V input #2	22	AGND	analogue ground <sup>1</sup>	42	RX485_N	not used
3	AIN3	0...5V input #3	23	AGND	analogue ground <sup>1</sup>	43	CAN1_T	Connect to CAN1_P to terminate CAN1
4	AIN4	0...5V input #4	24	AGND	analogue ground <sup>1</sup>	44	CAN1_P	CAN1 positive
5	AIN5	0...5V input #5	25	POWER	max 18V DC	45	CAN2_P	CAN2 positive
6	AIN6	0...5V input #6	26	SHIELD	shield	46	CAN2_T	Connect to CAN2_P to terminate CAN2
7	AIN7	0...5V input #7	27	GND_PWR	ground supply <sup>1</sup>	47	TX232	Tx RS232 <sup>3</sup>
8	AIN8	0...5V input #8	28	GND_DIN	digital ground	48	TX485_P	not used
9	AIN9	0...5V input #9	29	MARKER	spare digital input	49	TX485_N	not used
10	AIN10	0...5V input #10	30	BEACON	track marker (internal pull-up 10kΩ to 5V)	50	CAN1_N	CAN1 negative
11	AIN11	0...5V input #11	31	CODELOAD	ground for codeload - do not connect on car loom	51	ETHTX_P	Tx Ethernet positive <sup>3</sup>
12	AIN12	0...5V input #12	32	GND_232	ground RS232 <sup>1</sup>	52	CAN2_N	CAN2 negative
13	AIN13	0...5V input #13	33	GND_485	ground RS485 <sup>1</sup>	53	ETHRX_P	Rx Ethernet positive <sup>3</sup>
14	AIN14	0...5V input #14	34	GND_CAN	ground CAN1&2 <sup>1</sup>	54	ETHRX_N	Rx Ethernet negative <sup>3</sup>
15	AIN15	0...5V input #15	35	GND_IC	digital input capture ground <sup>1</sup>	55	ETHTX_N	Tx Ethernet negative <sup>3</sup>
16	AIN16	0...5V input #16	36	IC_1	internal pull-up 10kΩ to 5V			
17	VREF	5V reference <sup>2</sup>	37	IC_2	internal pull-up 10kΩ to 5V			
18	VREF	5V reference <sup>2</sup>	38	IC_3	internal pull-up 10kΩ to 5V			
19	VREF	5V reference <sup>2</sup>	39	IC_4	internal pull-up 10kΩ to 5V			
20	AGND	Analogue ground <sup>1</sup>	40	RX232	Rx RS232 <sup>3</sup>			



## Application notes

### PC RJ45 Ethernet connection



<sup>1</sup> All grounds connected internally

<sup>2</sup> Max. 50 mA total combined output of VREFs

<sup>3</sup> All Rx and Tx as seen from data logger